

OMG Data-Distribution Service (DDS): Architectural Overview

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Topic Areas	Software Architectures, Reusability, Scalability, and Standards Middleware Libraries and Application Programming Interfaces Fault-Tolerant Hardware and Software Techniques
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Summary

The OMG Data-Distribution Service (DDS) is a new specification for publish-subscribe data-distribution systems. The purpose of the specification is to provide a common application-level interface that clearly defines the data-distribution service. The specification describes the service using UML, providing a platform-independent model that can then be mapped into a variety of concrete platforms and programming languages.

This paper introduces the OMG DDS specification, describes the main aspects of the model, compares it with related technologies, and gives examples of the communication scenarios it supports.

This paper and presentation will clearly explain the important differences between **data-centric publish-subscribe** and **object-centric client-server** (e.g. CORBA) communications, along with the applicability of each for real-time systems.

The OMG DDS attempts to unify the common practice of several existing implementations enumerating and providing formal definitions for the Quality of Service (QoS) settings that can be used to configure the service.

Publish-subscribe networking is a key component of the Navy Open Systems Architecture (**Navy OA**) initiative. This talk will also highlight practical publish-subscribe implementations in Navy systems such as LPD 17, SSDS, and DD(X).

Background

The goal of the DDS specification is to facilitate the efficient distribution of data in a distributed system. Participants using DDS can “read” and “write” data efficiently and naturally with a typed interface. Underneath, the DDS middleware will distribute the data so that each reading participant can access the “most-current” values. In effect, the service creates a global “data space” that any participant can read and write. It also creates a name space to allow participants to find and share objects.

Report Documentation Page				Form Approved OMB No. 0704-0188	
Public reporting burden for the collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to a penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.					
1. REPORT DATE 01 FEB 2005		2. REPORT TYPE N/A		3. DATES COVERED -	
4. TITLE AND SUBTITLE OMG Data-Distribution Service (DDS)				5a. CONTRACT NUMBER	
				5b. GRANT NUMBER	
				5c. PROGRAM ELEMENT NUMBER	
6. AUTHOR(S)				5d. PROJECT NUMBER	
				5e. TASK NUMBER	
				5f. WORK UNIT NUMBER	
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) Real-Time Innovations, Inc. (RTI)				8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)				10. SPONSOR/MONITOR'S ACRONYM(S)	
				11. SPONSOR/MONITOR'S REPORT NUMBER(S)	
12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release, distribution unlimited					
13. SUPPLEMENTARY NOTES See also ADM001742, HPEC-7 Volume 1, Proceedings of the Eighth Annual High Performance Embedded Computing (HPEC) Workshops, 28-30 September 2004. , The original document contains color images.					
14. ABSTRACT					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT UU	18. NUMBER OF PAGES 28	19a. NAME OF RESPONSIBLE PERSON
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified			

DDS targets real-time systems; the API and QoS are chosen to balance predictable behavior and implementation efficiency/performance. We will note some of these tradeoffs in this paper.

Data-Centric versus Object-Centric communications models

Central to understanding the need for this new standard is an examination of the fundamental architectural differences between a “data-centric” and “object-centric” view of information communicated in a distributed real-time system.

DDS provides a natural counterpoint to the existing well-known CORBA model in which method invocations on remote objects are accessed through an interface defined in the Interface Descriptor Language (IDL). With CORBA, data is communicated indirectly through arguments in the method invocations or through their return values.

However, in many real-time applications the communications pattern is often modeled as pure data-centric exchange where applications publish supply or stream) “data” which is then available to the remote applications that are interested in it. Of primary concern is the efficient distribution of data with minimal overhead and the need to scale to hundreds or thousands of subscribers in a robust, fault-tolerant manner. These types of applications can be found in C4I systems, distributed control and simulation, telecom equipment control, and network management.

Comparison to Distributed Shared Memory

Additional requirements of many real-time applications include the need to control QoS properties that affect the predictability, overhead, and resources used. Distributed shared memory is a classic model that provides data-centric exchanges. However, this model is particularly difficult and “unnatural” to implement efficiently over the Internet.

Therefore, another model, the Data-Centric Publish-Subscribe (DCPS) model, has become popular in many real-time applications. While there are several commercial and in-house developments providing this type of facility, to date, there have been no general-purpose data-distribution standards. As a result, no common models directly support a data-centric system for information exchange.

The OMG Data-Distribution Service (DDS) is an attempt to solve this situation. The specification also defines the operations and QoS attributes each of these objects supports and the interfaces an application can use to be notified of changes to the data or wait for specific changes to occur.

Comparison to existing OMG Notification Service

This paper will examine the fact that, while it is theoretically possible for an application developer to use the OMG Notification Service to propagate the changes to data structures to provide the functionality of the DDS, doing this would be significantly complex because the

Notification Service does not have a concept of data objects or data-object instances nor does it have a concept of state coherence.

Comparison to existing High-Level Architecture (HLA) Run-Time Infrastructure (RTI)

HLA, also known as the OMG Distributed Simulation Facility, is a standard from both IEEE and OMG. It describes a data-centric publish-subscribe facility and a data model. The OMG specification is an IDL-only specification and can be mapped on top of multiple transports. The specification address some of the requirements of data-centric publish subscribe: the application uses a publish-subscribe interface to interact with the middleware, and it includes a data model and supports content-based subscriptions.

However, the HLA data model supports a specialization hierarchy, but not an aggregation hierarchy. The set of types defined cannot evolve over time. Moreover, the data elements themselves are un-typed and un-marshaled (they are plain sequences of octets). HLA also offers no generic QoS facilities.

Applications

This paper will describe the successful implementation of data-centric publish-subscribe communications in distributed modeling and simulation (M&S) as well as deployed Navy systems (pending release permissions). The presentation can include examples (depending on audience interest and familiarity) such as:

Ship:	Raytheon/Lockheed Martin LPD-17 Program
Ground:	CLIP/LINK tactical communications Program
Air:	F-35 JSF EW Subsystem
Space:	NASA Robonaut Program

DDS

Data Distribution Service

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DDS Standard



Data Distribution Service for Real-Time Systems

- Adopted in June 2003
- Finalized in June 2004
- Joint submission (RTI, THALES, MITRE, OIS)
- API specification for Data-Centric Publish-Subscribe communication for distributed real-time systems.

RTI's role

- Member of OMG since 2000
- Co-authors of the original DDS RFP
- Co-authors of the DDS specification adopted in June 2003
- Chair of the DDS Finalization Task Force completed March 2004
- Chair of the DDS Revision Task Force
- Providers of a COTS implementation of the specification (NDDS.4.0)



OMG Middleware standards

CORBA

Distributed object

- Client/server
- Remote method calls
- Reliable transport

Best for

- Remote command processing
- File transfer
- Synchronous transactions

DDS

Distributed data

- Publish/subscribe
- Multicast data
- Configurable QoS

Best for

- Quick dissemination to many nodes
- Dynamic nets
- Flexible delivery requirements

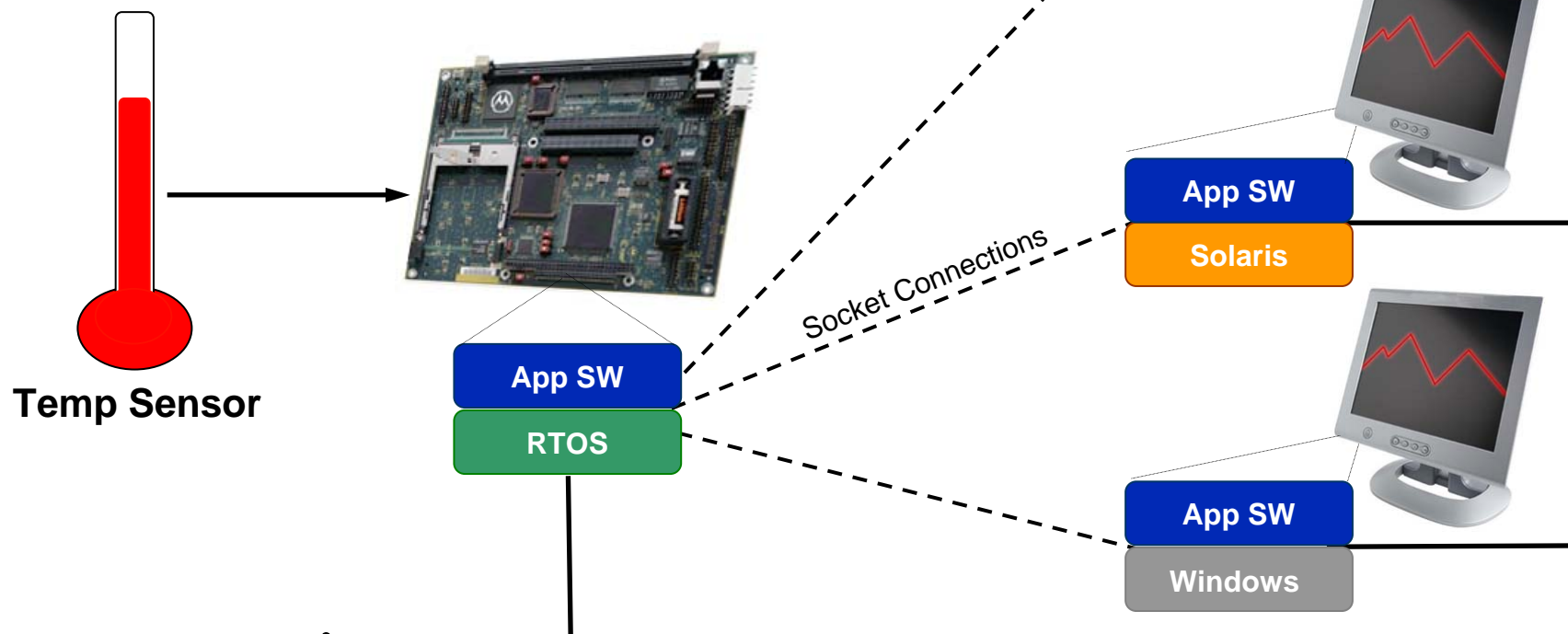
DDS and CORBA address different needs



Complex systems often need both...

More Complex Distributed Application

- New nodes are not dynamically “Discovered”
- Socket connections needed for each path
- Future upgrades require “re-design”
- App SW must perform endian conversion



The net-centric vision

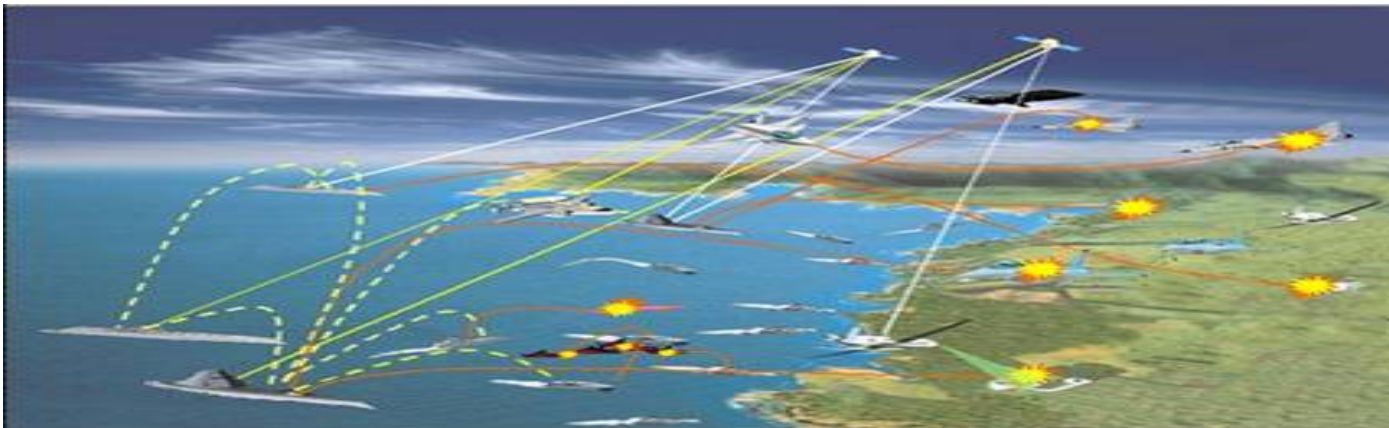
Vision for “net-centric applications”

Total access to information for real-time applications

This vision is enabled by the internet and related network technologies

Challenge:

“Provide the right information at the right place at the right time... no matter what.”



Challenges: Factors driving DDS

Need for speed

- Large networks, multicast
- High data rates
- Natural asynchrony
- Tight latency requirements
- Continuously-refreshed data



Complex data flows

- Controlled QoS: rates, reliability, bandwidth
- Per-node, or per-stream differences
- Varied transports (incl. Unreliable e.g. wireless)

Dynamic configurations

- Fast location transparency

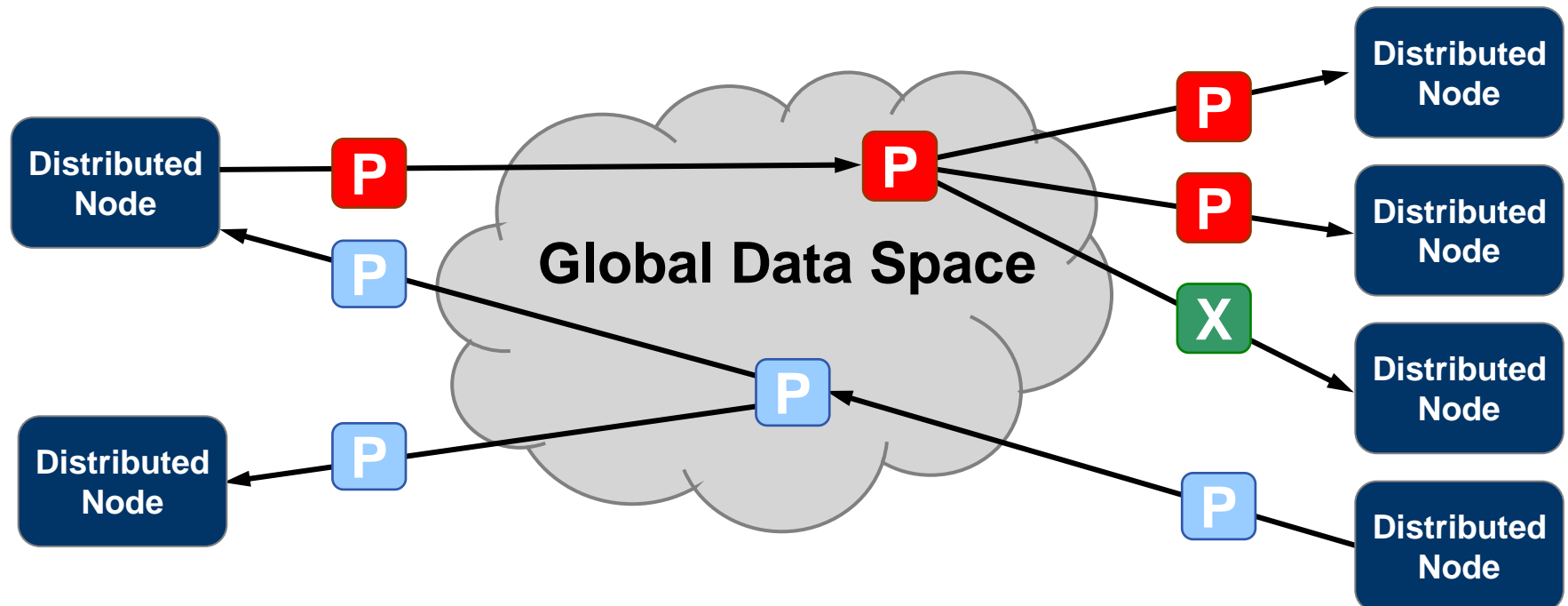
Fault tolerance

- No single-points of failure
- Transparent failover



Provides a “Global Data Space” that is accessible to all interested applications.

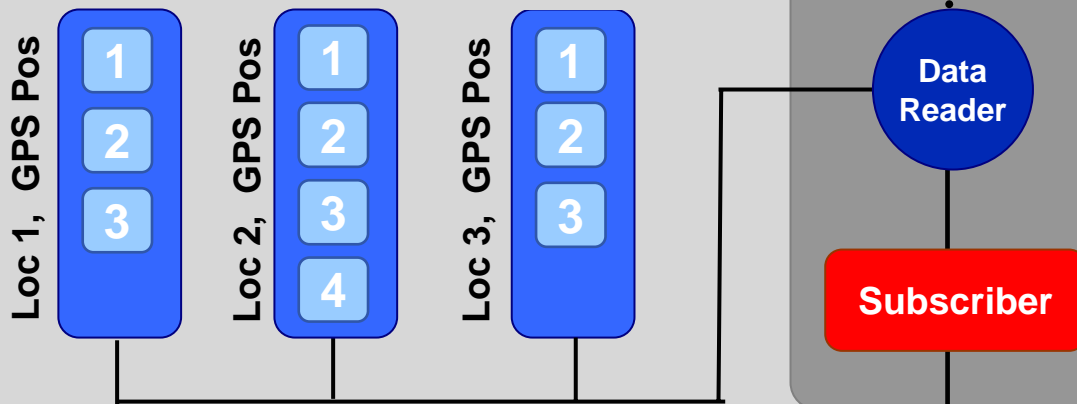
- Data objects addressed by **Topic** and **Key**
- Subscriptions are **decoupled** from Publications
- Contracts established by means of **QoS**
- Automatic **discovery** and configuration



Data object addressing: Keys

Address in Global Data Space = (Topic, Key)
Multiple instances of the same topic

- Used to sort specific instances
- Do not need a separate Topic for each data-object instance

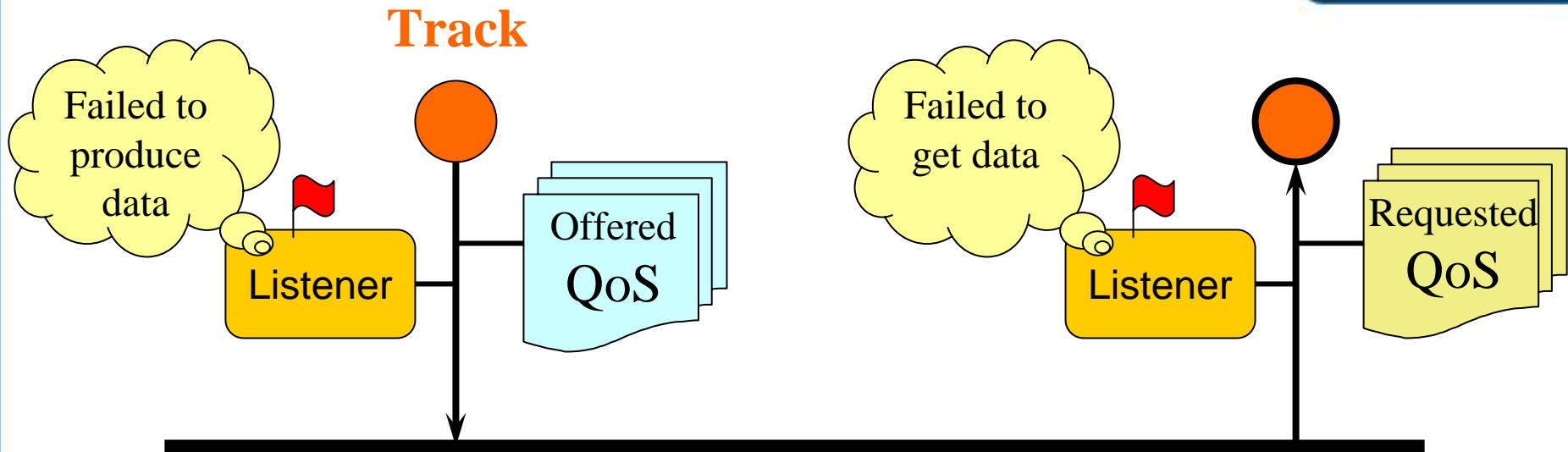


- Topic key can be any field within the Topic.

Example:

```
struct LocationInfo  
{  
    int LocID; //key  
    GPSPos pos;  
};
```

DDS communications model



Publisher declares information it has and specifies the Topic

- ... and the offered QoS contract
- ... and an associated listener to be alerted of any significant status changes

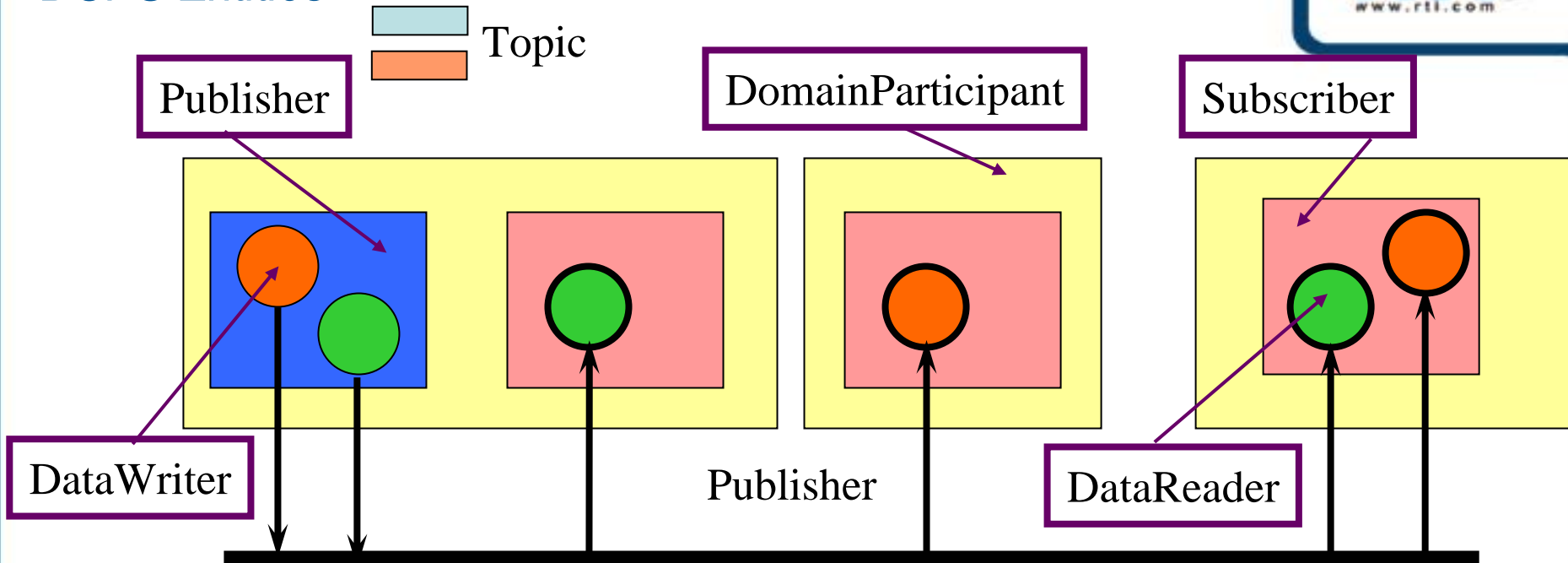
Subscriber declares information it wants and specifies the Topic

- ... and the requested QoS contract
- ... and an associated listener to be alerted of any significant status changes

DDS automatically discovers publishers and subscribers

- DDS ensures QoS matching and alerts of inconsistencies

DCPS Entities



DomainParticipant ~ Represents participation of the application in the communication collective

DataWriter ~ Accessor to write typed data on a particular Topic

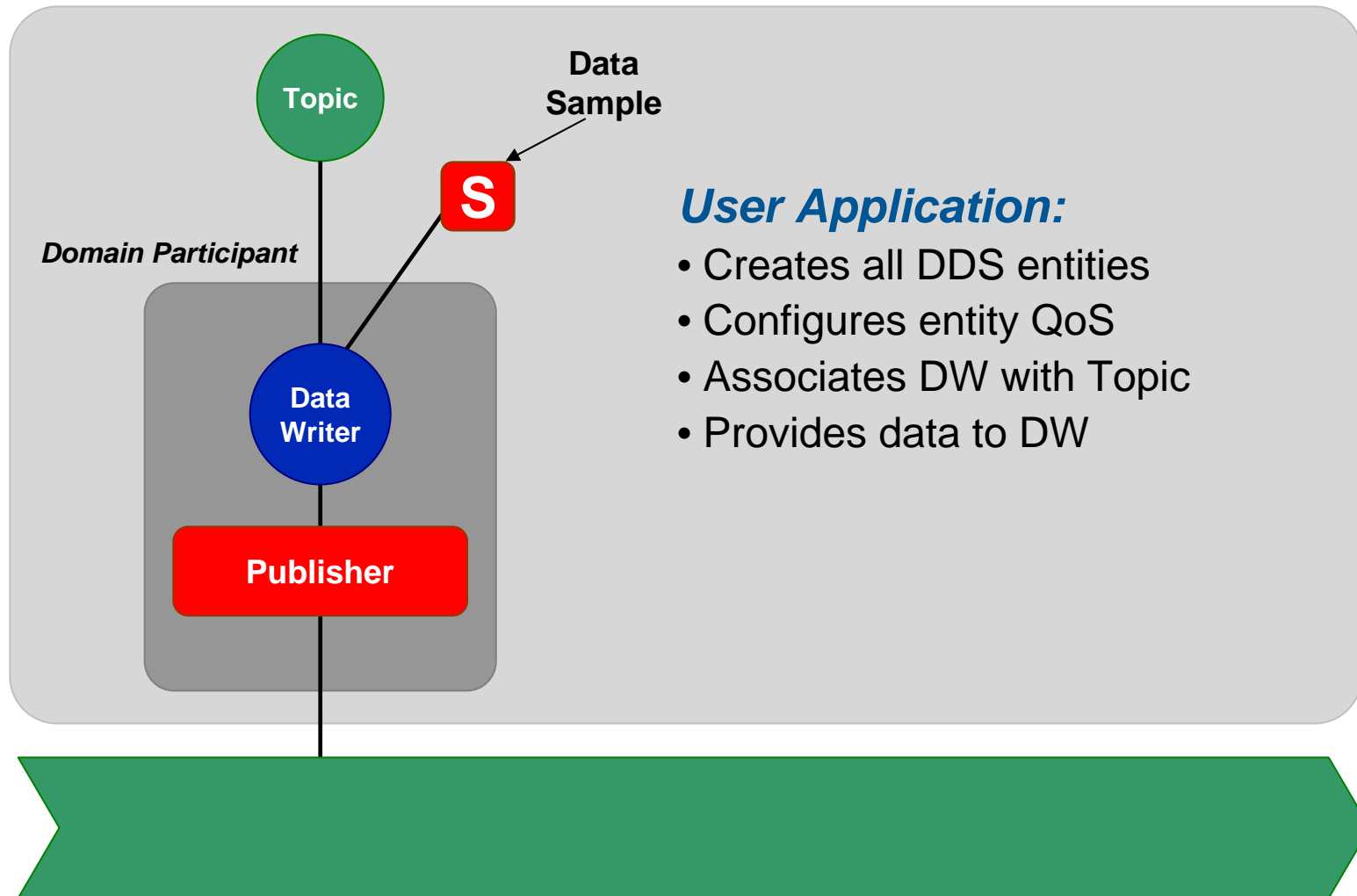
Publisher ~ Aggregation of DataWriter objects. Responsible for disseminating information.

DataReader ~ Accessor to read typed data regarding a specific Topic

Subscriber ~ Aggregation of DataReader objects. Responsible for receiving information



DDS Publication



Example: Publication

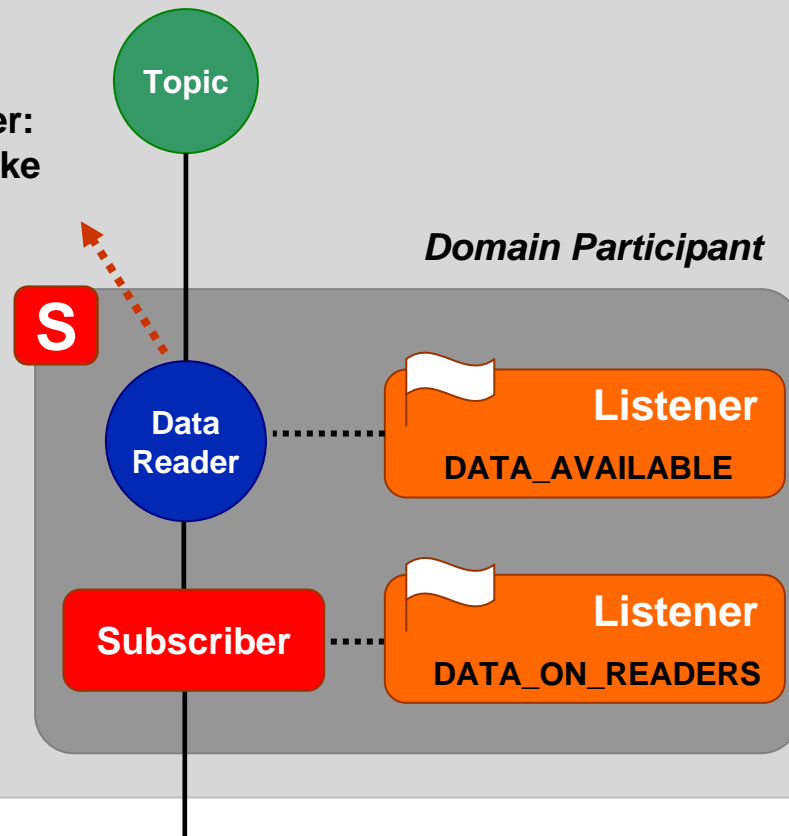
```
Publisher publisher = domain->create_publisher(  
    publisher_qos,  
    publisher_listener);  
  
Topic topic = domain->create_topic(  
    "Track", "TrackStruct",  
    topic_qos, topic_listener);  
  
DataWriter writer = publisher->create_datawriter(  
    topic, writer_qos, writer_listener);  
TrackStructDataWriter twriter =  
    TrackStructDataWriter::narrow(writer);  
  
TrackStruct my_track;  
twriter->write(&my_track);
```

DDS Subscription Listener

User Application:

- Creates all DDS entities
- Configures entity QoS
- Associates DR with Topic
- Receives Data from DR using a Listener

Listener:
read,take



Example: Subscription

```
Subscriber subs = domain->create_subscriber(  
    subscriber_qos, subscriber_listener);
```

```
Topic topic = domain->create_topic(  
    "Track", "TrackStruct",  
    topic_qos, topic_listener);
```

```
DataReader reader = subscriber->create_datareader(  
    topic, reader_qos, reader_listener);
```

```
// Use listener-based or wait-based access
```

How to get data (listener-based)

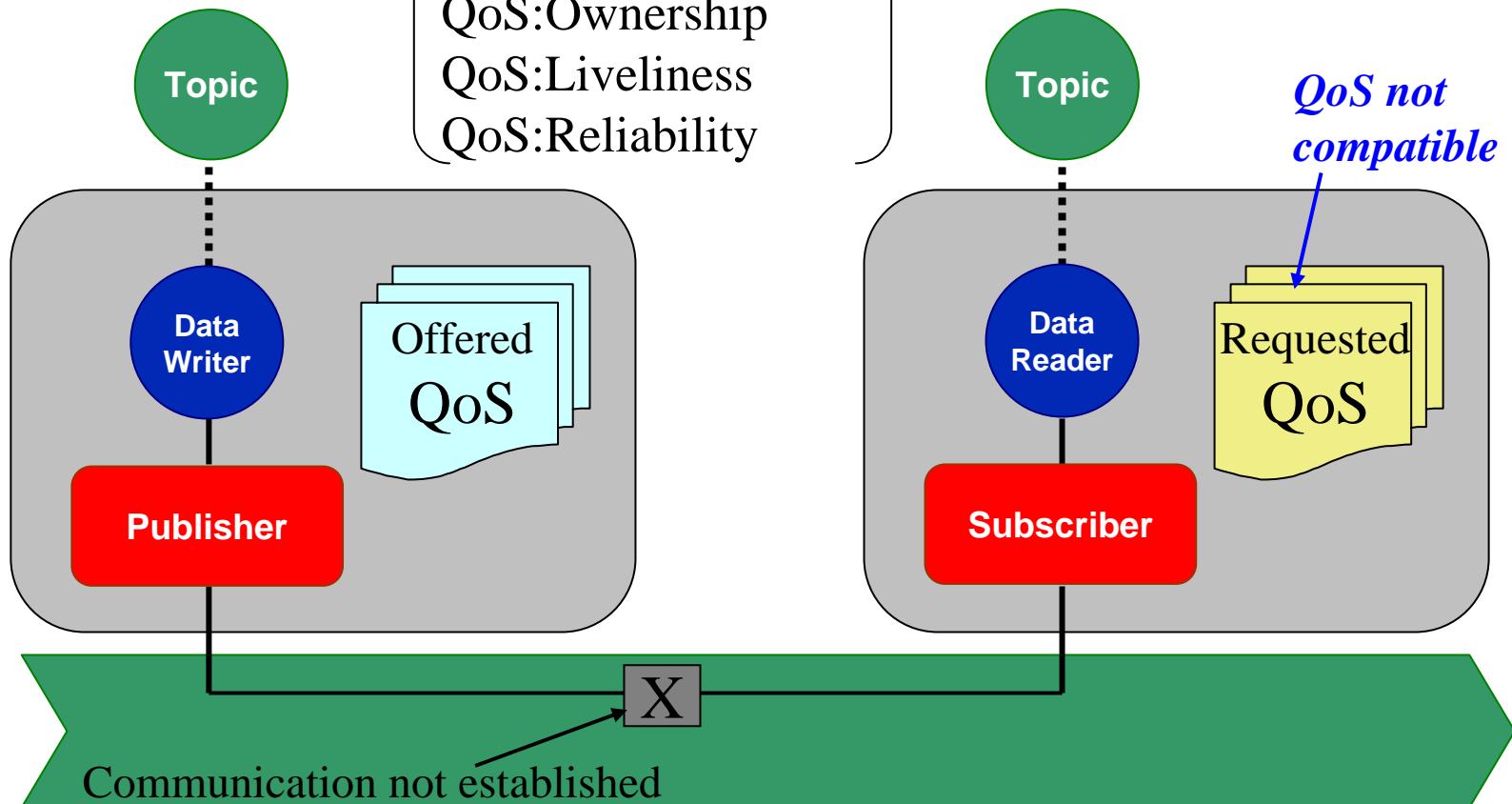
```
Listener listener = new MyListener();  
reader->set_listener(listener);
```

```
MyListener::on_data_available( DataReader reader )  
{  
    TrackStructSeq received_data;  
    SampleInfoSeq sample_info;  
    TrackStructDataReader treader =  
        TrackStructDataReader::narrow(reader);  
  
    treader->take( &received_data,  
                  &sample_info, ...)  
  
    // Use received_data  
}
```

QoS Contract “Request / Offered”

QoS:Durability
QoS:Presentation
QoS:Deadline
QoS:Latency_Budget
QoS:Ownership
QoS:Liveliness
QoS:Reliability

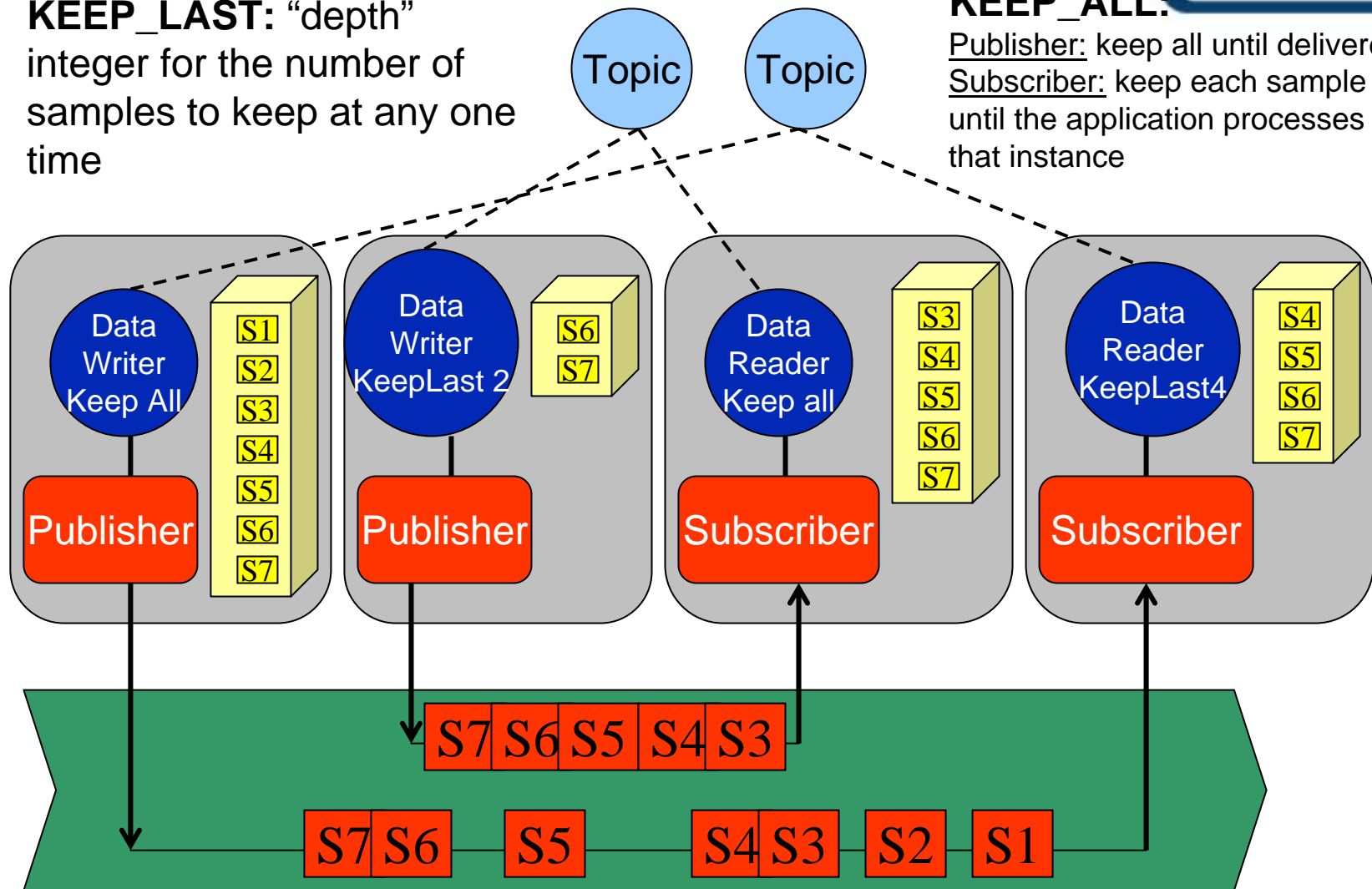
QoS Request / Offered:
*Ensure that the compatible
QoS parameters are set.*



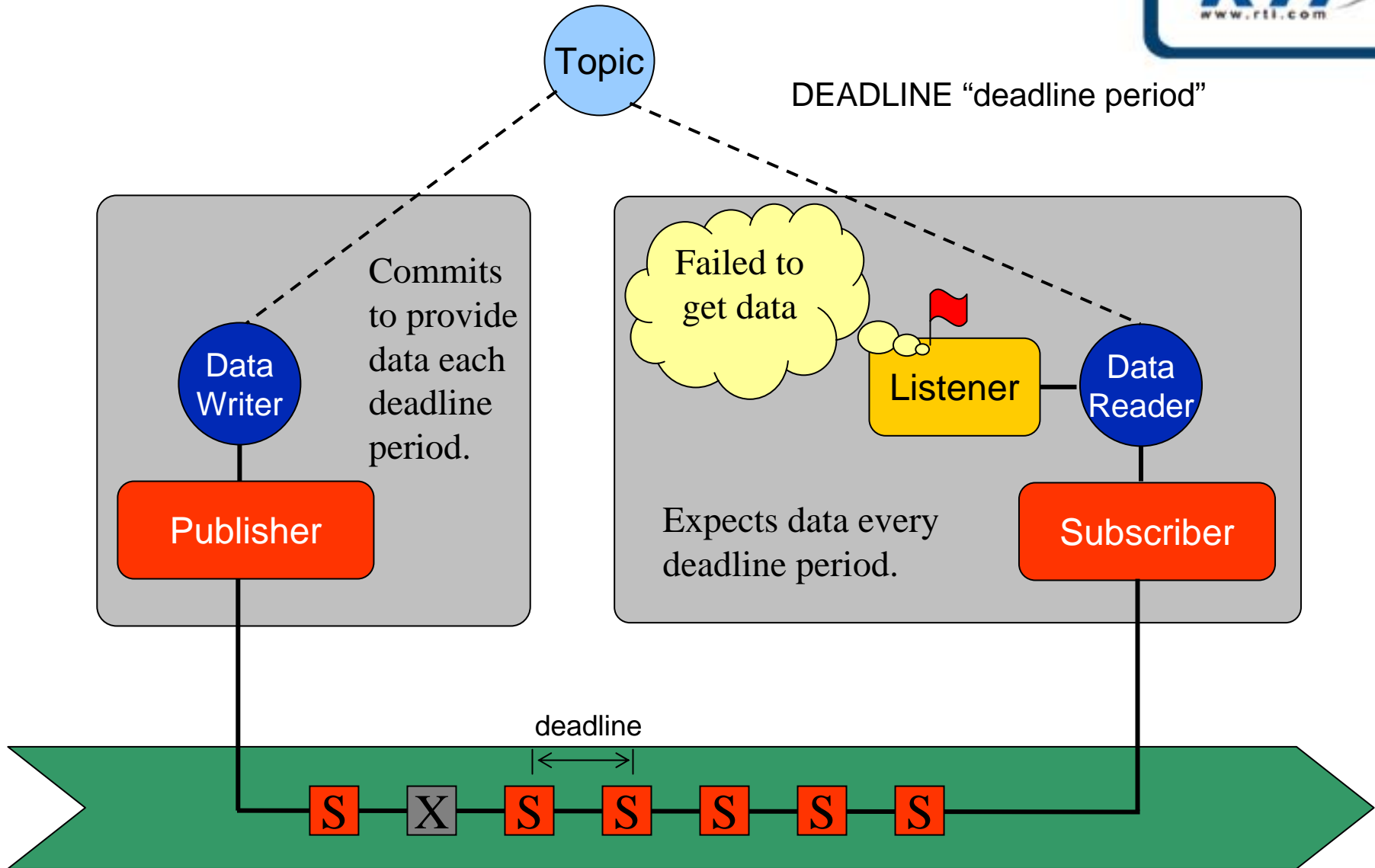
QoS: History: Last x or All

KEEP_LAST: “depth”
integer for the number of
samples to keep at any one
time

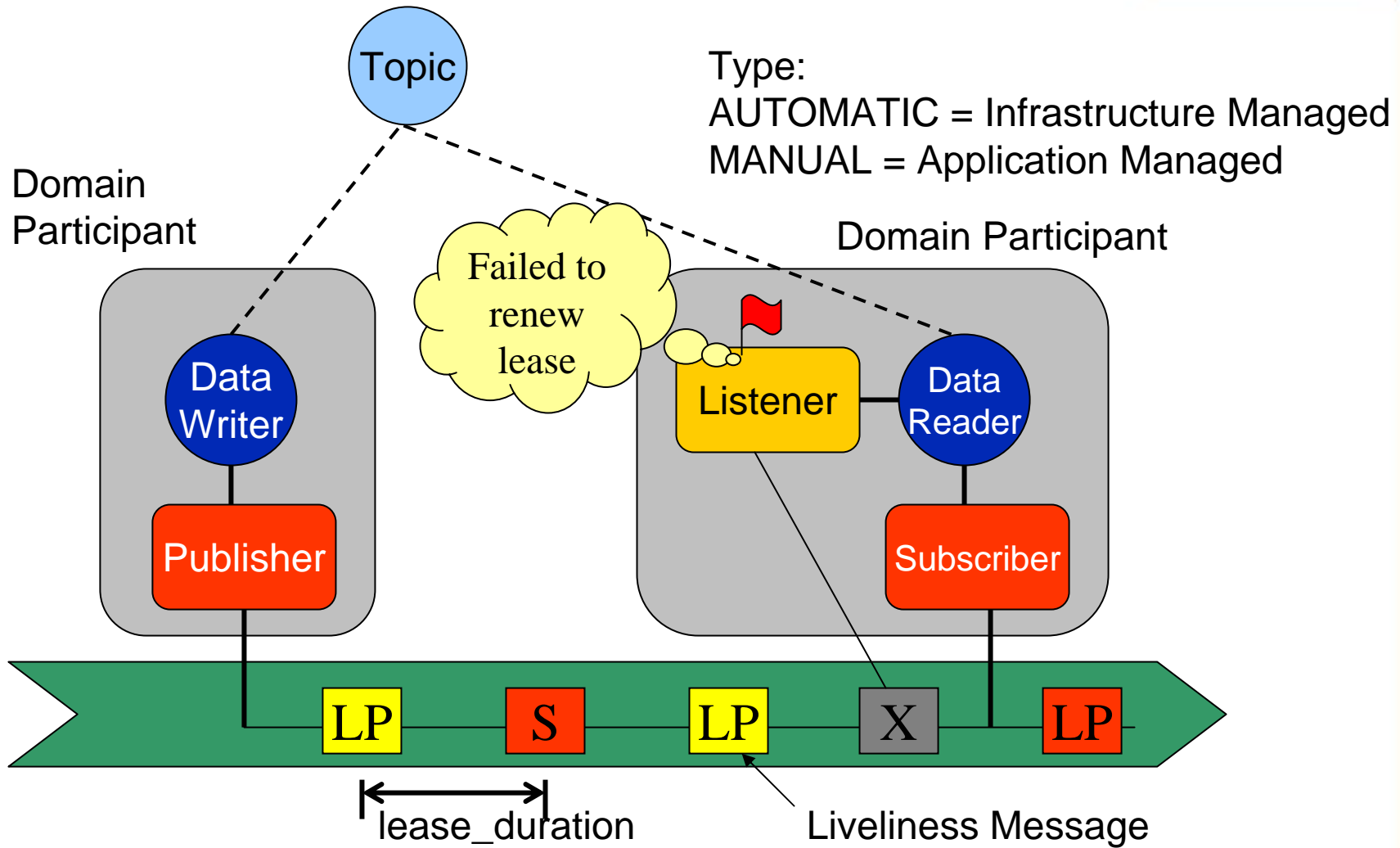
KEEP_ALL:
Publisher: keep all until delivered
Subscriber: keep each sample
until the application processes
that instance



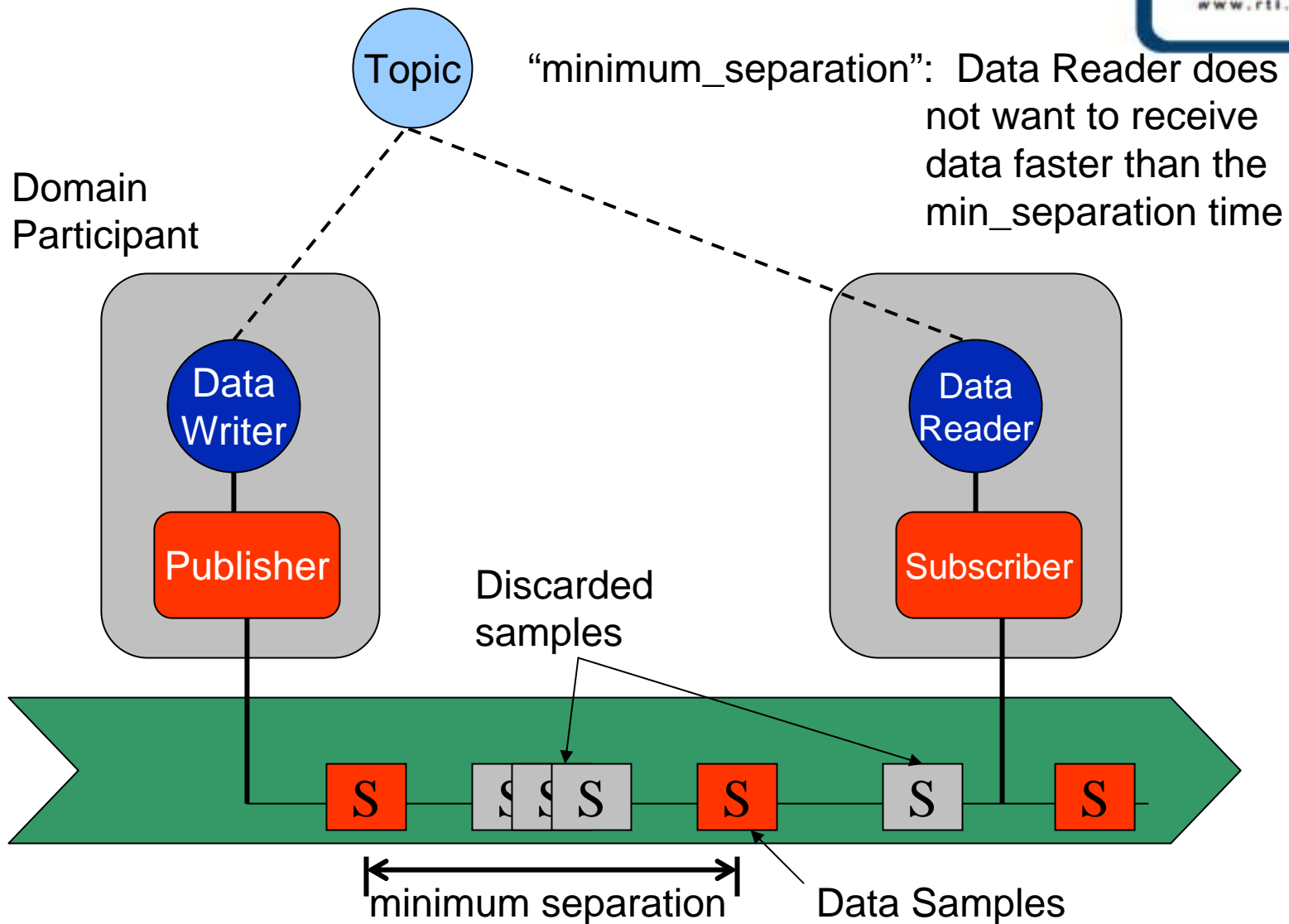
QoS: Deadline



QoS: Liveliness – Type, Duration



QoS: Time_Based_Filter



QoS: Quality of Service (1/2)

QoS Policy	Concerns	RxO	Changeable
DEADLINE	T,DR,DW	YES	YES
LATENCY BUDGET	T,DR,DW	YES	YES
READER DATA LIFECYCLE	DR	N/A	YES
WRITER DATA LIFECYCLE	DW	N/A	YES
TRANSPORT PRIORITY	T,DW	N/A	YES
LIFESPAN	T,DW	N/A	YES
LIVELINESS	T,DR,DW	YES	NO
TIME BASED FILTER	DR	N/A	YES
RELIABILITY	T,DR,DW	YES	NO
DESTINATION ORDER	T,DR	NO	NO

QoS: Quality of Service (2/2)

QoS Policy	Concerns	RxO	Changeable
USER DATA	DP,DR,DW	NO	YES
TOPIC DATA	T	NO	YES
GROUP DATA	P,S	NO	YES
ENTITY FACTORY	DP, P, S	NO	YES
PRESENTATION	P,S	YES	NO
OWNERSHIP	T	YES	NO
OWNERSHIP STRENGTH	DW	N/A	YES
PARTITION	P,S	NO	YES
DURABILITY	T,DR,DW	YES	NO
HISTORY	T,DR,DW	NO	NO
RESOURCE LIMITS	T,DR,DW	NO	NO

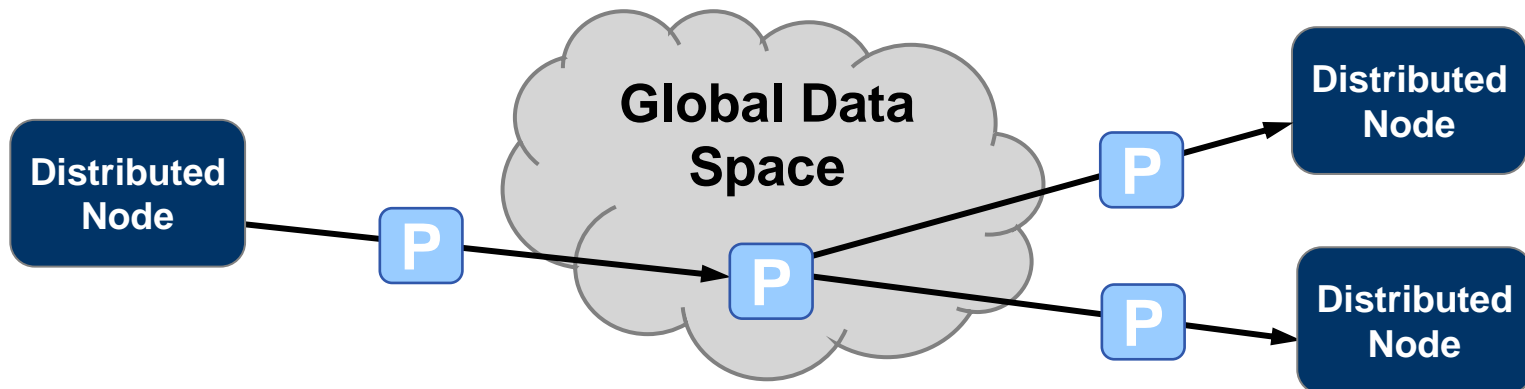
Summary

DDS targets applications that need to distribute data in a real-time environment

DDS is highly configurable by QoS settings

DDS provides a shared “global data space”

- Any application can publish data it has
- Any application can subscribe to data it needs
- Automatic discovery
- Facilities for fault tolerance
- Heterogeneous systems easily accommodated



Thank you

References:

OMG DDS specification:

<http://www.omg.org/cgi-bin/doc?ptc/04-04-12>

General material on DDS and RTI's implementation:

<http://www.rti.com/dds>

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